



The Future of Analog IC Technology®

## MP4057A

Single-Stage Single Chip  
Solution for Smart LED

### DESCRIPTION

The MP4057A is a single-chip/single-stage solution for smart LED applications that can regulate LED current with primary-side regulation (PSR) control and supply power for microcontroller units (MCU) and wireless modules. The MP4057A is the most ideal solution for smart LED lighting because of its simplest design, fewest external components, and lowest cost.

The MP4057A achieves a high power factor and accurate LED current. The proprietary real-current-control method accurately controls LED current from the primary-side information. The MP4057A integrates power-factor correction and works in valley switching mode to reduce MOSFET switching loss.

The MP4057A achieves ultra-low standby loss (typically 30mW no-load power) by decreasing the working frequency in standby mode.

The MP4057 has an integrated charging circuit at the supply pin for fast start-up without a perceptible delay.

Based on the information from DIM, the MP4057A can operate in two operation modes: constant current (CC) and constant-voltage (CV). The LED can turn off when the MP4057A works in CV mode. During the transition between CC and CV, the LED does not flicker, and the voltage of the MCU/wireless module does not drop.

The MP4057A's multiple protection features enhance system reliability and safety greatly. These features include over-voltage protection (OVP), short-circuit protection (SCP), primary-side over-current protection (OCP), brown-out protection, cycle-by-cycle current limiting protection, under-voltage lockout (UVLO), and auto-restart over-temperature protection (OTP).

The MP4057A is available in MSOP-10 and SOIC14 packages.

### FEATURES

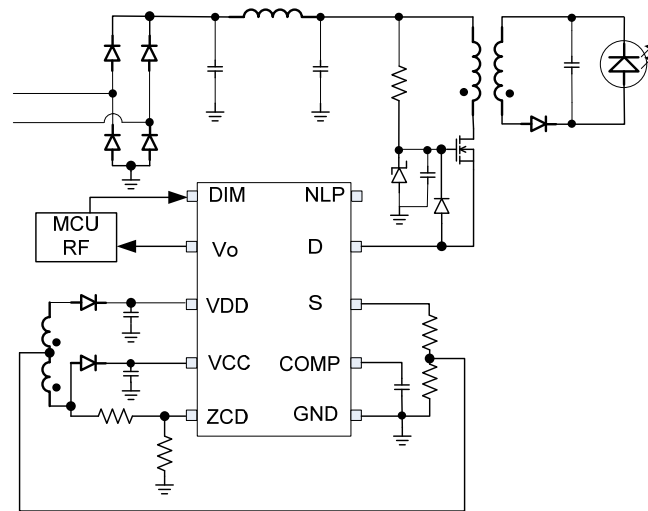
- Single-Chip/Single-Stage with LED Driver and Power Supply for MCU/Wireless Modules
- Fast Start-Up
- Ultra-Low Standby Loss, Typically Less Than 30mW in No-Load Condition, Optional Circuit for Less than 15mW at No Load
- 5% Deep Dimming
- No Flicker
- Low Audible Noise
- Valley Switching Mode in CC Mode for Good Efficiency
- Good Power Factor (PF) (Typically >0.9)
- Good Transient Response
- Cycle-by-Cycle Current Limit Protection in CV Mode
- Primary-Side Over-Current Protection (OCP)
- Output Over-Voltage Protection (OVP) and Short-Circuit Protection (SCP)
- Under-Voltage Lockout (UVLO)
- Thermal Shutdown (160°C/100°C)
- Available in MSOP-10 and SOIC14 Packages

### APPLICATIONS

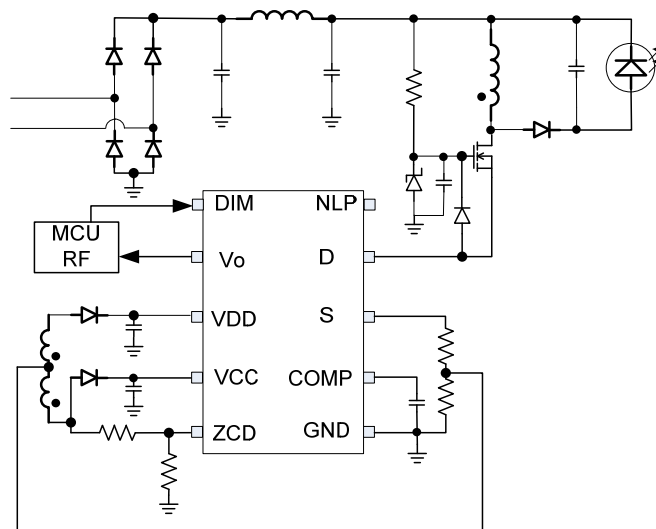
- Zigbee/Bluetooth Smart Lighting
- DALI or Dmax Dimming Protocol

All MPS parts are lead-free, halogen-free, and adhere to the RoHS directive. For MPS green status, please visit the MPS website under Quality Assurance. "MPS" and "The Future of Analog IC Technology" are registered trademarks of Monolithic Power Systems, Inc.

## TYPICAL APPLICATION



**Isolated Flyback Application**



**Non-Isolated Buck-Boost Application**

## ORDERING INFORMATION

Part Number	Package	Top Marking
MP4057AGK*	MSOP-10	See Below
MP4057AGS**	SOIC-14	

\* For Tape & Reel, add suffix -Z (e.g. MP4057AGK-Z)

\*\* For Tape & Reel, add suffix -Z (e.g. MP4057AGS-Z)

## TOP MARKING (MP4057AGK)

YWLLL

4057A

Y: Year code

W: Week code

LLL: Lot number

4057A: First five digits of the part number

## TOP MARKING (MP4057AGS)

MPSYYWW

MP4057A

LLLLLLLLLL

MPS: MPS prefix

YY: Year code

WW: Week code

MP4057A: Product code of MP4057AGS

LLLLLLLLLL: Lot number



## ELECTRICAL CHARACTERISTICS

Typical values are tested at VDD = VCC = 12V, T<sub>J</sub> = +25°C, unless otherwise noted. Minimum and maximum values are tested at VDD = VCC = 12V, T<sub>J</sub> = -40°C to +125°C, unless otherwise noted, guaranteed by characterization.

Parameter	Symbol	Condition	Min	Typ	Max	Units
<b>Supply Voltage (VDD)</b>						
Operating range	VDD	After turn-on	3.5		27	V
VDD upper level: internal charging circuit stops and the IC turns on	VDD <sub>H</sub>	VDD rising edge	10	10.5	11	V
VDD lower level: if VCC is lower than VDD, internal charging circuit is triggered and IC stops switching, UVLO occurs	VDD <sub>L</sub>	VDD falling edge	5.2	5.5	5.8	V
VDD operation hysteretic voltage	VDD <sub>HYS</sub>		4.75	5	5.25	V
VDD low level for high-frequency mode	VDD <sub>enter</sub>	VDD falling edge at CC mode	4.27	4.5	4.73	V
VDD <sub>enter</sub> hysteretic (to exit transient mode)	VDD <sub>enter_Hys</sub>			1.03		V
<b>Supply Voltage (VCC)</b>						
Operating range	VCC	After turn-on	3.5		27	V
VCC regulated value at CV	VCC <sub>regulate</sub>	With VO 50mA load	4.35	4.6	4.85	V
VCC upper level for UVLO	VCC <sub>H</sub>	VCC rising edge	10.2	10.8	11.4	V
VCC lower level: if VDD is lower than VCC, internal charging circuit is triggered and IC stops switching, UVLO occurs	VCC <sub>L</sub>	VCC falling edge	5.2	5.5	5.8	V
VCC voltage for start-up	VCC <sub>startup</sub>	VCC rising edge	4	4.2	4.4	V
VCC high-frequency mode (enter) @ CV	VCC <sub>enter_CV</sub>	VCC falling edge @ CV	3.6	3.8	4	V
VCC <sub>enter</sub> hysteretic @ CV	VCC <sub>enter_Hys_CV</sub>			0.4		V
VCC high-frequency mode (enter) @ CC	VCC <sub>enter_CC</sub>	VCC falling edge @ CC	6	6.3	6.6	V
VCC <sub>enter</sub> hysteretic @ CC	VCC <sub>enter_Hys_CC</sub>			1		V

## ELECTRICAL CHARACTERISTICS (continued)

Typical values are tested at VDD = VCC = 12V, T<sub>J</sub> = +25°C, unless otherwise noted. Minimum and maximum values are tested at VDD = VCC = 12V, T<sub>J</sub> = -40°C to +125°C, unless otherwise noted, guaranteed by characterization.

Parameter	Symbol	Condition	Min	Typ	Max	Units
<b>Supply Current</b>						
VDD charging current from D	I <sub>D-charge</sub>	V <sub>D</sub> = 16V, VDD = VCC = 10.5V	25	35	50	mA
Operating current	I <sub>operating</sub>	1. COMP = V <sub>COMP_L</sub> 2. CV operation			330	μA
		1. COMP = 1.8V 2. CV operation 3. 30kHz switch frequency			500	μA
		1. 60kHz switch frequency 2. CC operation			1	mA
Operating current under fault condition	I <sub>fault</sub>	Fault condition, IC latch, VCC = VDD = 15V	0.95	1.35	1.8	mA
Pull-down current when UVLO	I <sub>pull_down_UVLO</sub>	VCC = VDD = 5V	0.75	1.05	1.65	mA
Leakage current on D	I <sub>leakage-D</sub>				1	μA
<b>LDO</b>						
Maximum voltage drop for VO	V <sub>drop_VO</sub>	With 50mA VO current			0.2	V
Maximum current limit for VO	I <sub>LDO_max</sub>	VDD = VCC = 10V	100			mA
<b>VO</b>						
Output voltage of VO	VO		3.2	3.3	3.4	V
VO_OK threshold	VOH		2.95	3.1	3.25	V
VO_OK hysteresis	VO_Hys			0.28		V
<b>DIM</b>						
High level	V <sub>dim_H</sub>		1.13	1.25	1.37	V
Low level	V <sub>dim_L</sub>		0.27	0.3	0.33	V
Maximum DIM detect time to determine the frequency of PWM dimming signal	t <sub>dim_detect</sub>		7	9.5	13	ms
<b>Error Amplifier (EA)</b>						
Feedback voltage	V <sub>FB</sub>		0.196	0.203	0.210	V
Transconductance @ CC <sup>(6)</sup>	G <sub>EA</sub>	CC		250		μA/V
Max source current <sup>(6)</sup>	I <sub>COMP+</sub>			50		μA
Max sink current <sup>(6)</sup>	I <sub>COMP-</sub>			-200		μA
Upper clamp voltage for CC	V <sub>COMP_H_CC</sub>		3.8	4	4.2	V
Transconductance @ CV <sup>(6)</sup>	G <sub>EA</sub>	CV		50		μA/V
Upper clamp voltage for CV	V <sub>COMP_H_CV</sub>	CV	2.5	2.65	2.8	V
Lower clamp voltage	V <sub>COMP_L</sub>		1.15	1.21	1.27	V

## ELECTRICAL CHARACTERISTICS (continued)

Typical values are tested at VDD = VCC = 12V, T<sub>J</sub> = +25°C, unless otherwise noted. Minimum and maximum values are at VDD = VCC = 12V, T<sub>J</sub> = -40°C to +125°C, unless otherwise noted, guaranteed by characterization.

Parameter	Symbol	Condition	Min	Typ	Max	Units
PWM Comparator						
Slope rate of normal operation	$\alpha$		0.35	0.395	0.44	V/ $\mu$ s
Slope rate of CC transient operation	$\alpha_{\text{transient}}$	Zero detected and VO > 3.1V	0.06	0.11	0.16	V/ $\mu$ s
Minimum on time	$t_{\text{min\_ON\_time}}$	CV	260	390	530	ns
		CC	700	1050	1400	
Zero-Current Detector (ZCD)						
Bias current of ZCD	$I_{\text{bias\_ZCD}}$	During turn on	290	350	400	$\mu$ A
Brown-out protection threshold	$V_{\text{brown out}}$		0.16	0.19	0.22	V
Brown-out detection time	$t_{\text{brown out}}$		14	19	25	ms
Zero-current detect threshold	$V_{\text{ZCD\_T}}$	$V_{\text{ZCD}}$ falling edge	0.25	0.3	0.4	V
Zero-current hysteresis for CV	$V_{\text{ZCD\_hys\_CV}}$		0.27	0.3	0.33	V
Zero-current hysteresis for CC	$V_{\text{ZCD\_hys\_CC}}$		0.57	0.6	0.63	V
ZCD blanking time	$t_{\text{LEB\_ZCD}}$	Only for CC, after turn-off, $V_{\text{s\_peak}} > 0.15\text{V}$	1	1.5	2	$\mu$ s
		1. For CV 2. For CC, after turn-off, $V_{\text{s\_peak}} < 0.15\text{V}$	0.5	0.7	0.9	
Over-voltage blanking time	$t_{\text{LEB\_ZCD}}$	Only for CC, after turn-off, $V_{\text{s\_peak}} > 0.15\text{V}$	1	1.5	2	$\mu$ s
		1. For CV 2. For CC, after turn-off, $V_{\text{s\_peak}} < 0.15\text{V}$	0.5	0.7	0.9	
Over-voltage threshold	$V_{\text{ZCD\_OVP}}$	1.5 $\mu$ s delay after turn-off	4.25	4.55	4.8	V
Fault Pull-Up MOSFET						
Breakdown voltage	$BV_{\text{DSS\_D\_VCC}}$		30			V
Continue drain current	$I_{\text{D\_D\_VCC}}$		8	11.5	15	mA
CV Minimum Off Time						
Maximum off time	$t_{\text{max\_OFF\_CV}}$	COMP = $V_{\text{COMP\_L}}$	1.5	2.5	3.5	ms
Minimum off time in CV mode	$t_{\text{min\_OFF\_CV}}$	COMP = $V_{\text{COMP\_H\_CV}}$	25	37	47	$\mu$ s
CC Minimum Off Time						
Minimum off time in CC mode	$t_{\text{min\_OFF\_CC}}$		2.4	3	4.2	$\mu$ s
Maximum off time	$t_{\text{max\_OFF\_CC}}$	COMP = $V_{\text{COMP\_L}}$	30	43	57	$\mu$ s

## ELECTRICAL CHARACTERISTICS (continued)

Typical values are tested at VDD = VCC = 12V, T<sub>J</sub> = +25°C, unless otherwise noted. Minimum and maximum values are tested at VDD = VCC = 12V, T<sub>J</sub> = -40°C to +125°C, unless otherwise noted, guaranteed by characterization.

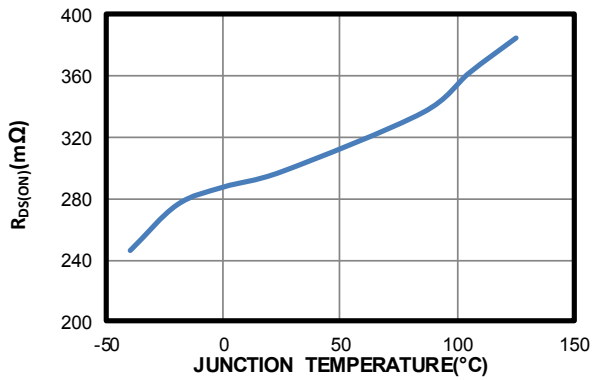
Parameter	Symbol	Condition	Min	Typ	Max	Units
<b>S Pin</b>						
Blanking time for S	t <sub>blank_S</sub>		260	390	530	ns
Blanking time for short inductor/transformer	t <sub>blank_S_short</sub>			280		ns
<b>Starter</b>						
Start timer period	t <sub>START</sub>	ZCD not detected	130	160	190	μs
<b>Current Limit</b>						
CV mode current limit	V <sub>cv_limit</sub>	With S blanking, T <sub>blank_S</sub>	0.42	0.45	0.49	V
CC mode current limit	V <sub>CC_limit</sub>	With S blanking, T <sub>blank_S</sub>	1.39	1.47	1.55	V
CV mode current limit foldback	V <sub>cv_limit_foldback</sub>	With S blanking, T <sub>blank_S</sub>	0.17	0.2	0.23	V
CV mode current limit @ high-frequency mode	V <sub>cv_limit_HF</sub>	With S blanking, T <sub>blank_S</sub>	0.61	0.65	0.69	V
Primary over-current protection	V <sub>primary_OCP</sub>	With S blanking, T <sub>blank_S_short</sub>	1.85	2	2.15	V
<b>NLP</b>						
Leakage current	I <sub>leakage_NLP</sub>	NLP=20V			350	nA
R <sub>DS(ON)</sub> of pull-down MOSFET	R <sub>dson_NLP</sub>			145	300	Ω
<b>Internal Main MOSFET</b>						
Break-down voltage	BV <sub>DSS_Main</sub>	V <sub>gs</sub> = 0	30			V
Drain-source on resistor	R <sub>DS(ON)_Main</sub>	I <sub>D</sub> = 500mA		300		mΩ
<b>Thermal Shutdown</b>						
Thermal shutdown threshold	T <sub>SD</sub>			160		°C
Thermal shutdown recovery hysteresis	T <sub>hys</sub>			60		°C

### NOTE:

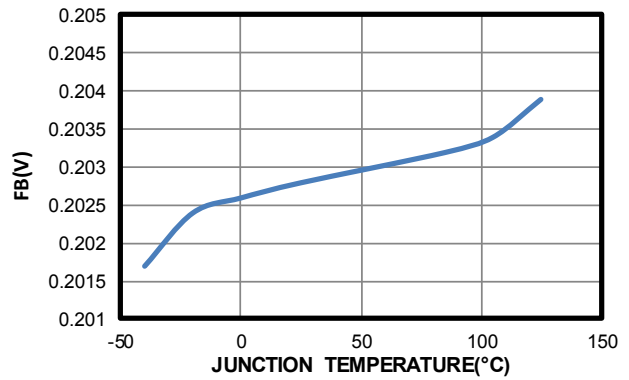
5) Guaranteed by design.

## TYPICAL CHARACTERISTICS

**Internal MOSFET  $R_{DS(ON)}$  vs. Junction Temperature**



**FB Reference Voltage vs. Junction Temperature**



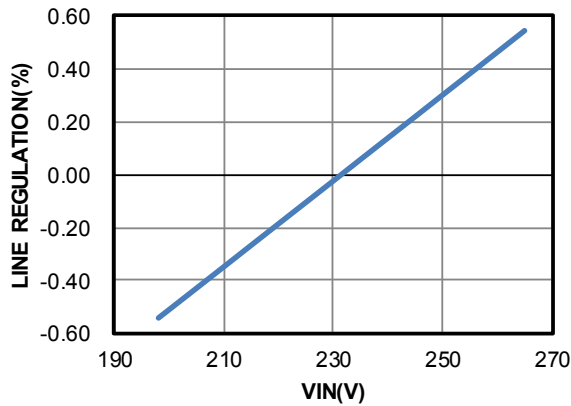
## TYPICAL PERFORMANCE CHARACTERISTICS

Performance waveforms are tested on the evaluation board EV4057A-K-00A.

$V_{IN} = 230V_{AC}/50Hz$ , 7LEDs in series,  $I_{LED} = 370mA$ ,  $V_{LED} = 21V$ ,  $L_p = 2.2mH$ .

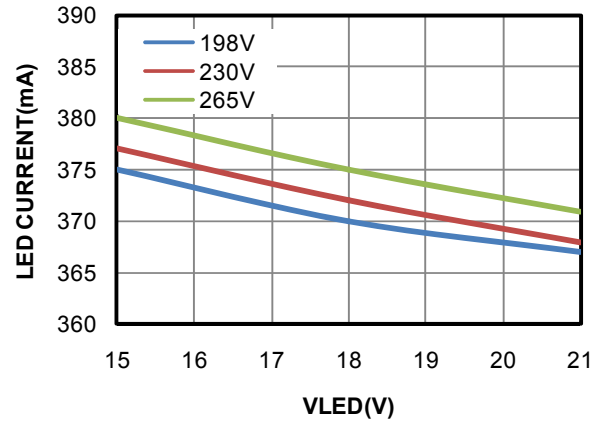
### Line Regulation

$V_{IN} = (198-265)V_{AC}/50Hz$ , Full Load



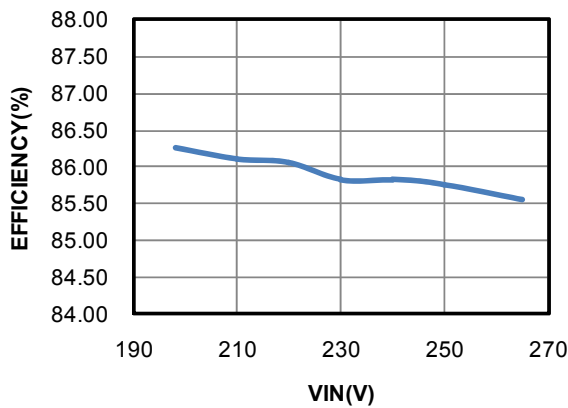
### Load Regulation

$V_{IN} = (198-265)V_{AC}/50Hz$ , full load



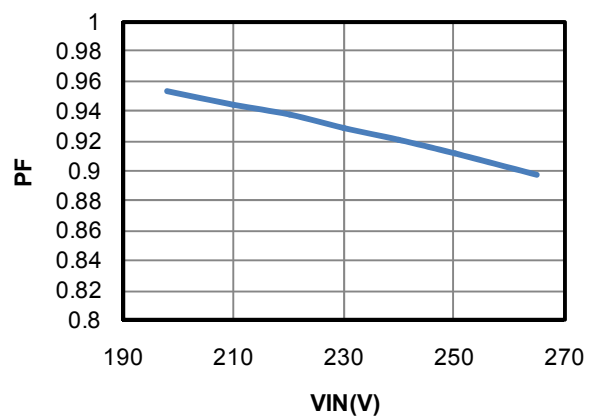
### Efficiency

$V_{IN} = (198-265)V_{AC}/50Hz$ , full load



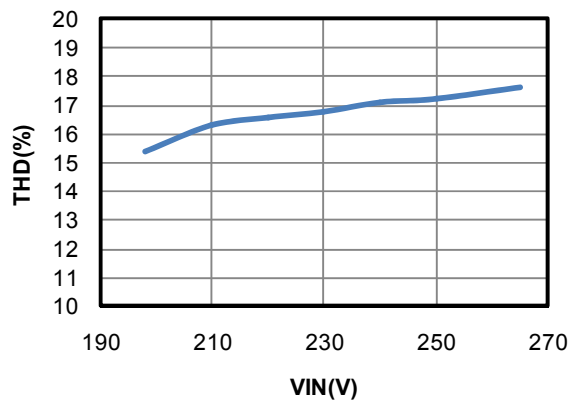
### PF

$V_{IN} = (198-265)V_{AC}/50Hz$ , full load



### THD

$V_{IN} = (198-265)V_{AC}/50Hz$ , full load



### Dimming Curve

$V_{IN} = 230V_{AC}$ , 7 LED output



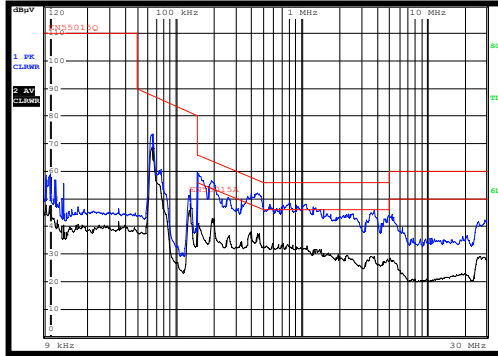
## TYPICAL PERFORMANCE CHARACTERISTICS *(continued)*

Performance waveforms are tested on the evaluation board EV4057A-K-00A.

$V_{IN} = 230V_{AC}/50Hz$ , 7 LEDs in series,  $I_{LED} = 370mA$ ,  $V_{LED} = 21V$ ,  $L_p = 2.2mH$ .

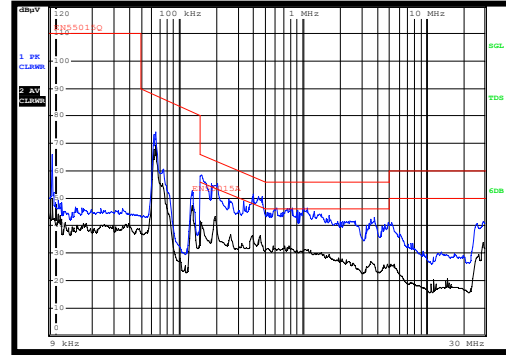
### Conduct EMI-L Line

$V_{IN} = 230V_{AC}$ , 7 LED output



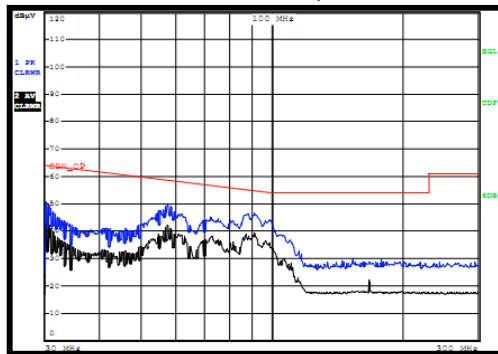
### Conduct EMI-N Line

$V_{IN} = 230V_{AC}$ , 7 LED output



### CDN

$V_{IN} = 230V_{AC}$ , 7 LED output



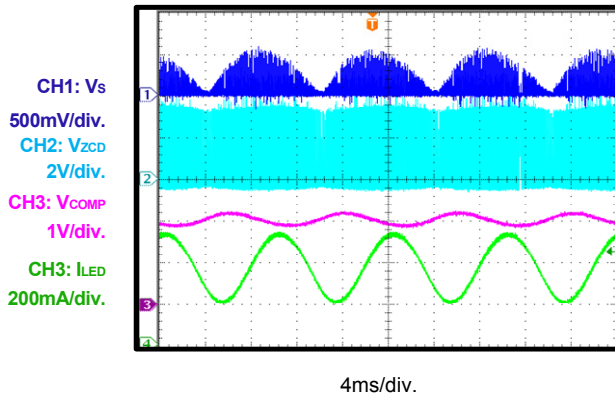
## TYPICAL PERFORMANCE CHARACTERISTICS (continued)

Performance waveforms are tested on the evaluation board EV4057A-K-00A.

$V_{IN} = 230V_{AC}/50Hz$ , 7 LEDs in series,  $I_{LED} = 370mA$ ,  $V_{LED} = 21V$ ,  $L_p = 2.2mH$ .

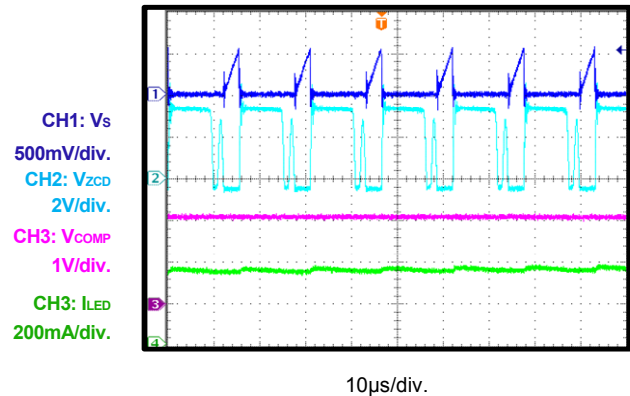
### Steady State

$V_{IN} = 230V_{AC}$ , 7 LED output



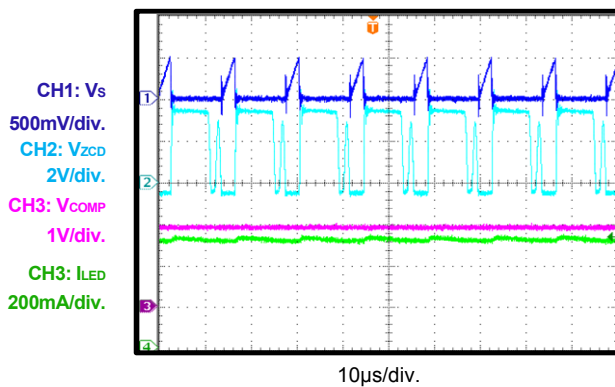
### Steady State

$V_{IN} = 230V_{AC}$ , 7 LED output



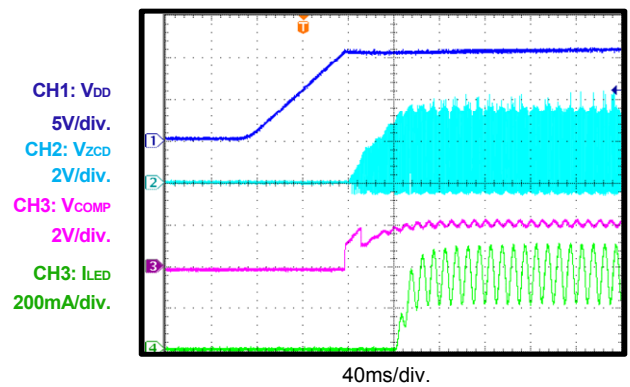
### Steady State

$V_{IN} = 230V_{AC}$ , 7 LED output



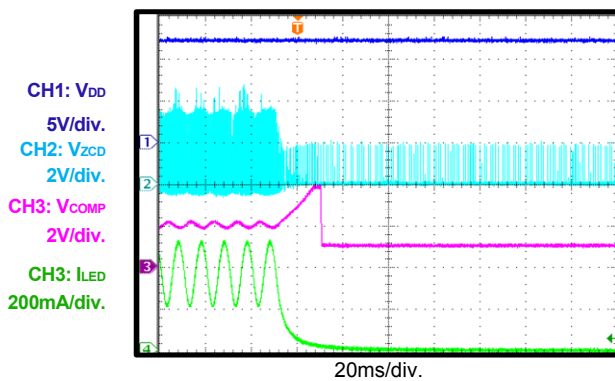
### Start-Up

$V_{IN} = 230V_{AC}$ , 7 LED output



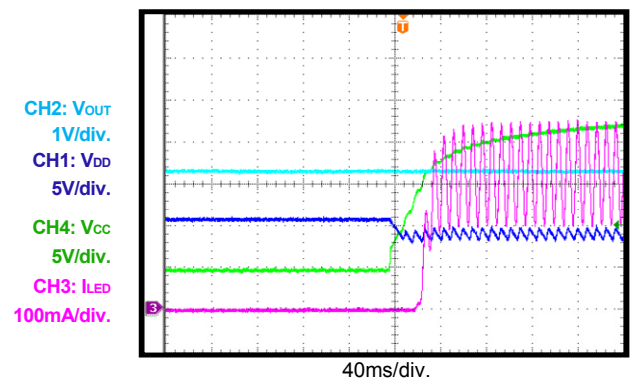
### Shutdown

$V_{IN} = 230V_{AC}$ , 7 LED output



### CV-CC

$V_{IN} = 230V_{AC}$ , 7 LED output, full load



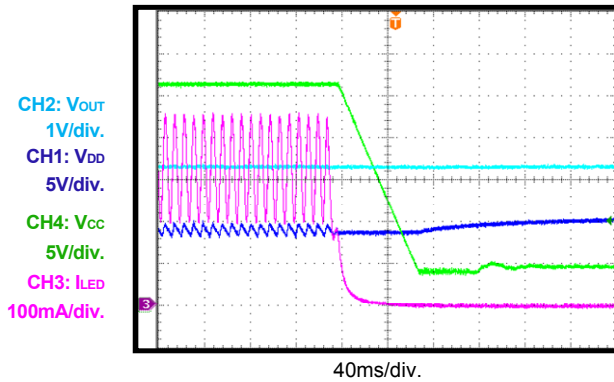
## TYPICAL PERFORMANCE CHARACTERISTICS *(continued)*

Performance waveforms are tested on the evaluation board EV4057A-K-00A.

$V_{IN} = 230V_{AC}/50Hz$ , 7 LEDs in series,  $I_{LED} = 370mA$ ,  $V_{LED} = 21V$ ,  $L_p = 2.2mH$ .

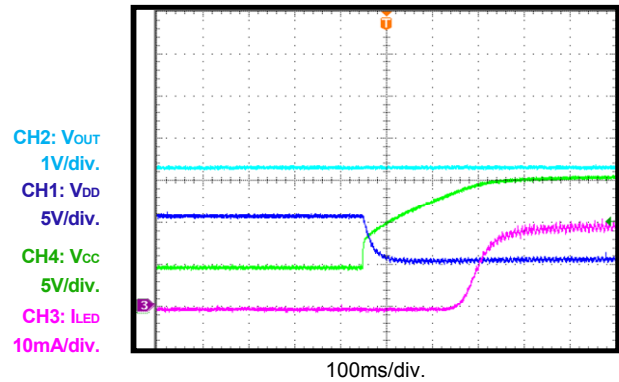
### CC-CV

$V_{IN} = 230V_{AC}$ , 7 LED output, full load



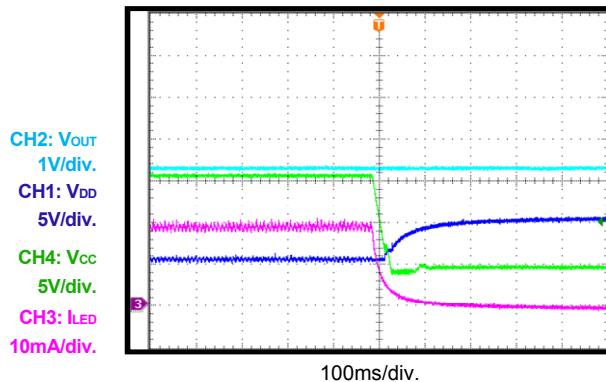
### CV-CC

$V_{IN} = 230V_{AC}$ , 7 LED output, DIM = 1%



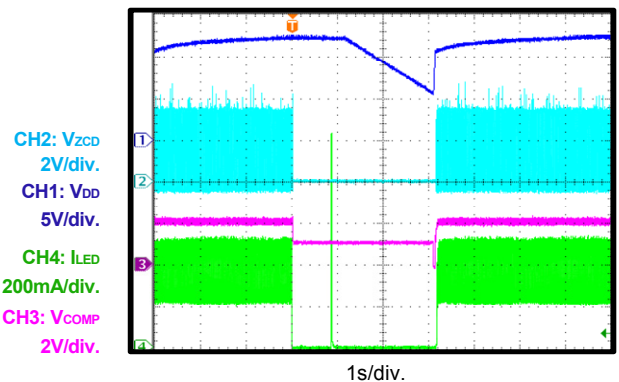
### CC-CV

$V_{IN} = 230V_{AC}$ , 7 LED output, DIM = 1%



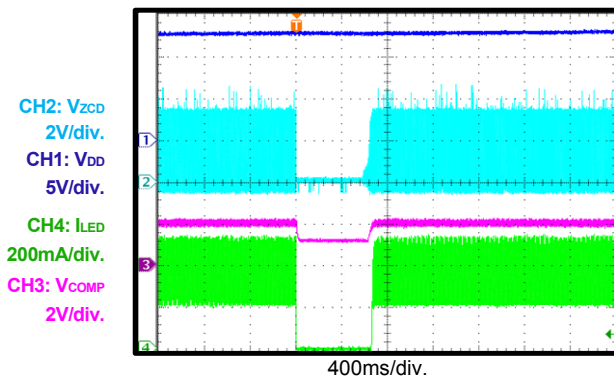
### OVP

$V_{IN} = 230V_{AC}$ , 7 LED output



### SCP

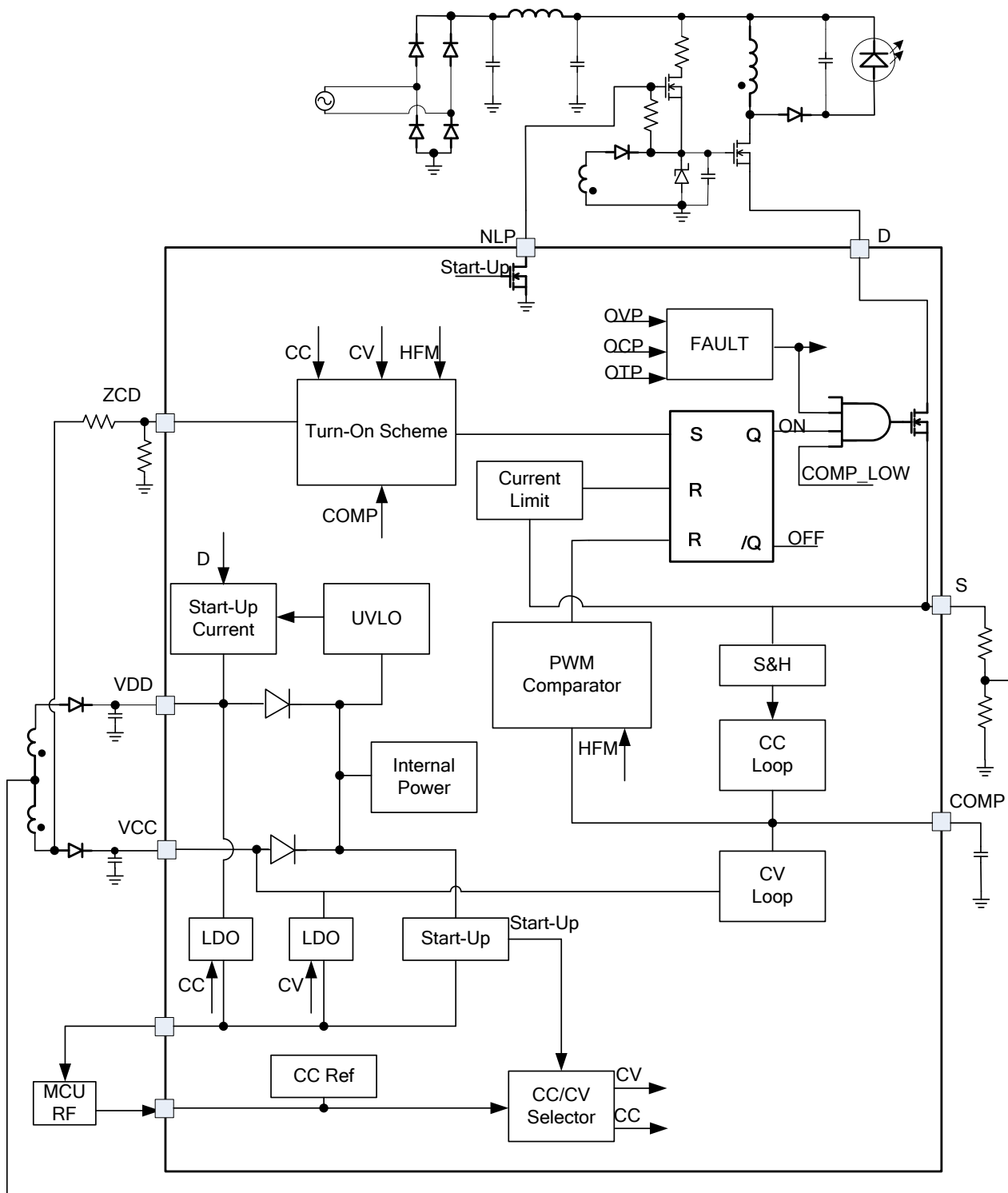
$V_{IN} = 230V_{AC}$ , 7 LED output



## PIN FUNCTIONS

Pin #		Name	Description
MSOP-10	SOIC14		
1	1	D	<b>Internal low-side main MOSFET drain.</b> D is connected to the source of the external high-side main MOSFET. D is also connected to VDD internally through a diode and a J-FET to form an internal charging circuit for VDD.
2	2	S	<b>Internal low-side main MOSFET source.</b> Connect a resistor from S to GND to sense the internal MOSFET current. In CC mode, the primary-side, real-current control is calculated with S. In CV mode, the system is protected by the current-limit function via S.
3	4	VCC	<b>Power supply input.</b> VCC supplies power to VO in CV mode. VCC also supplies power to the chip when VCC is higher than VDD.
4	5	COMP	<b>Loop compensation.</b> Both CC and CV use COMP as the loop compensation. Connect a compensation network to COMP to stabilize the loop.
5	6	ZCD	<b>Zero-current detection.</b> Connect ZCD to a resistor-divider between the auxiliary winding and GND. An over-voltage condition is detected through ZCD. For every turn-off interval, if the ZCD voltage exceeds the over-voltage-protection (OVP) threshold after the blanking time ( $t_{LEB\_ZCD}$ ) for four consecutive periods, OVP is triggered, and the system stops switching until auto-restart occurs. The input brown-out is detected by ZCD. For every turn-on interval, if ZCD is higher than $V_{brown\ out}$ during turn-on and lasts for at least $t_{brown\ out}$ , the MP4057A recognizes that a brown-out has occurred.
6	9	GND	<b>Ground.</b> GND is the current return for the control signal and gate-drive signal.
7	10	DIM	<b>LED dimming.</b> Apply an external PWM signal on DIM for LED dimming. Apply a low-level ( $<V_{dim\_L}$ ) signal to DIM to force the MP4057A to enter CV operation mode. Leave DIM floating to operate the MP4057A in CC.
8	11	VO	<b>3.3V output power.</b>
9	12	VDD	<b>Power supply input.</b> VDD supplies power to VO in CC mode. VDD also supplies power to the chip when VDD is higher than VCC.
10	14	NLP	<b>Control signal for active start-up device.</b> NLP is connected to the gate of the external depletion N-FET. NLP can disable the external HV current to save energy in standby mode.
-	3, 7, 8, 13	NC	<b>No connection.</b>

## BLOCK DIAGRAM



**Figure 1: Functional Block Diagram**

## OPERATION

The MP4057A is a single-chip/single-stage solution for smart LED applications that can regulate the LED current with primary-side regulation (PSR) control and supply power for microcontroller units (MCU)/wireless modules. According to the DIM information, the MP4057A operates in either constant-current (CC) or constant voltage (CV) mode. In CC mode, it accurately regulates the LED current using the real-current-control method based on the primary information. Good performance including high power factor (PF), regulation, deep dimming, and efficiency is achieved in CC mode. In CV mode, the MP4057A works with low frequency to save power loss. As a result, ultra-low no load power (typically 30mW) is achieved in this design. During the switch between CC and CV, there is no voltage drop in smart modules and no LED flicker.

### Start-Up

Initially, VDD is charged by the internal charging circuit from the AC line. When VDD reaches the  $V_{DDH}$  threshold, the under-voltage lockout (UVLO) logic changes to low, and the internal main MOSFET begins to switch. The MP4057A defaults in CV mode for start-up until VCC 4.2V and VO is 3.1V, which indicates the end of the start-up sequence. After UVLO becomes low, the internal charging circuit is disabled, and the power supply of the chip is taken over by whichever voltage of either VDD or VCC is higher. The start-up sequence is shown in Figure 2.

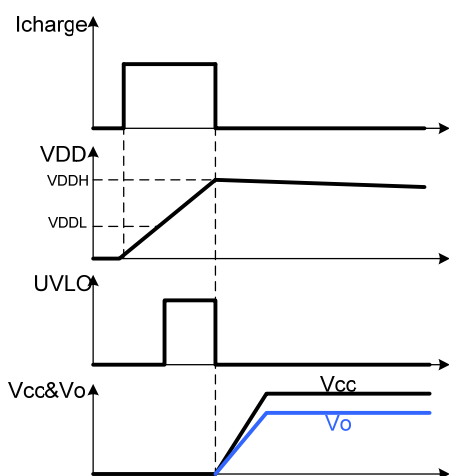


Figure 2: Start-Up Sequence

After start-up, the MP4057A selects its operation mode based on the information from DIM. If DIM is logic low, the MP4057A operates in CV mode. Otherwise, the MP4057A operates in CC mode.

### Constant-Voltage (CV) Operation

During CV operation, VCC is sensed by the error compensation amplifier. VCC is regulated and takes charge of the VO power. Due to the turns ratio relationship between the VCC winding and LED winding, the output LED is not light. It is suggested to add a dummy load on the LED output side to ensure zero LED current.

To achieve ultra-low input power in CV standby mode, there is an internal intelligent frequency modulation circuit to optimize the switching frequency.

If the system works in no-load condition, VCC may be higher than the regulated value due to the minimum on-time limit. The COMP voltage is clamped at 1.21V, and the minimum working frequency can drop down to around 400Hz.

In some applications during the load step of VO, especially from no load to the maximum load, VCC may drop due to the slow response of the voltage loop. To improve this, high-frequency operation (HFM) is adopted to guarantee no voltage drop on VO.

### CC Mode – PWM Dimming

During CC operation, the DIM information is sent to the error amplifier of CC. The feedback reference voltage is scaled down based on the DIM information. Therefore, the linear relationship between the LED current and DIM signal can be obtained. To ensure the power supply of the MCU/wireless module, the minimum feedback reference voltage is clamped at 10mV, and the maximum dimming depth is 5%.

### CC Mode – Valley Switching Mode Operation

Figure 3 shows a typical flyback converter. During the external MOSFET on time ( $t_{ON}$ ), the rectified input voltage ( $V_{BUS}$ ) is applied to the primary-side inductor ( $L_p$ ), and the primary current ( $I_{pri}$ ) increases linearly from zero to the peak value ( $I_{pk}$ ). When the external MOSFET turns off, the energy stored in the inductor is transferred to the secondary side and turns on

the secondary-side diode to power the load. The secondary current ( $I_{sec}$ ) begins to decrease linearly from the peak value to zero. When the secondary current decreases to zero, the primary-side leakage inductance, magnetizing the inductance and all parasitic capacitances decreases the MOSFET drain-source voltage. This decrease is also reflected on the auxiliary winding. During CC operation, the MP4057A monitors ZCD if it falls to zero twice before the next switching period. The zero-current detector from ZCD generates the gate turn-on signal when the ZCD voltage falls below 0.295V the second time (see Figure 4). This virtually eliminates switch turn-on loss and diode reverse-recovery loss, ensuring high efficiency and low EMI noise.

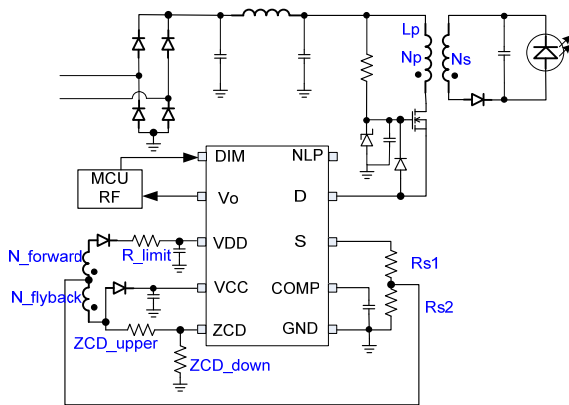


Figure 3: Typical Flyback Converter

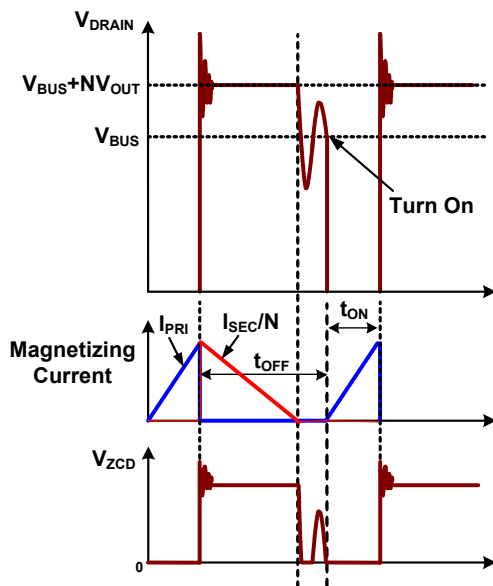


Figure 4: Valley Switching Mode

### CC Mode – Real Current Control

The proprietary real-current control method allows the MP4057A to control the secondary-side LED current from primary-side information. The mean output LED current can be calculated approximately with Equation (1):

$$I_o \approx \frac{N \cdot V_{FB}}{2 \cdot R_s} \quad (1)$$

Where N is the turn ratio of the primary side to the secondary side,  $V_{FB}$  is the feedback reference voltage (typically 0.203V), and  $R_s$  is the sensing resistor connected between the MOSFET source and GND.

### CC Mode – Decoupled Principle for MCU Power and LED Power

When the system works in CC mode, VDD takes over the VO output power. By forward-connecting the auxiliary winding and the current sensing resistor, the VO output power and LED current loop can be decoupled. The turn ratio relationship between the forward winding and the ratio between the two current sensing resistors must satisfy Equation (2):

$$\frac{N_{forward}}{N_p} \cdot R_{s1} = (1 - \frac{N_{forward}}{N_p}) \cdot R_{s2} \quad (2)$$

Where  $N_{forward}$  is the turns of the forward winding,  $N_p$  is the turns of the primary winding,  $R_{s1}$  is the sensing resistor connected to the MOSFET source, and  $R_{s2}$  is the sensing resistor connected to GND.

### CC Mode – Minimum Off Time

The MP4057A operates with a variable switching frequency. The frequency changes with the input instantaneous line voltage. To limit the maximum frequency and get a good EMI performance, the MP4057A employs an internal minimum off-time limiter ( $t_{min\_OFF\_CC}$ ).

By increasing the minimum off time in deep dimming conditions, the MP4057A can achieve a 5% dimming depth. The minimum off time is limited to  $t_{max\_OFF\_CC}$ , which helps hold VO during deep dimming.

### CC Mode – Power Factor Correction

The high power factor is guaranteed by the constant on-time theory. Use a fixed slope triangle to compare to the COMP voltage and obtain the constant  $T_{ON}$  in a certain  $V_{IN}$  and output loads. The constant on-time forces the primary peak current to follow the track of the input voltage, which achieves the high power factor (see Figure 5).

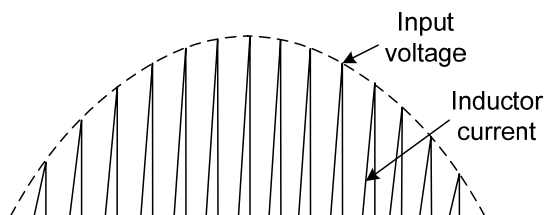


Figure 5: Constant  $T_{ON}$  for PFC

### Auto-Starter

The MP4057A integrates an auto-starter, which starts timing when the MOSFET is turned off. If ZCD fails to send out another turn-on signal after  $t_{START}$ , the starter sends out the turn-on signal automatically, which can prevent an unnecessary IC shutdown caused by ZCD missing a detection.

### Under-Voltage Lockout (UVLO)

If both VDD and VCC drop below the UVLO threshold 5.5V, the MP4057A stops switching and shuts down. The VDD restarts to be charged by the internal current source from the AC line.

### Leading Edge Blanking (LEB)

To avoid premature termination of the switching pulse due to parasitic capacitance discharging when the MOSFET turns on, an internal leading edge blanking (LEB) unit is employed between S and the current comparator input. During the blanking time, the path (S to the current comparator input) is blocked (see Figure 6).

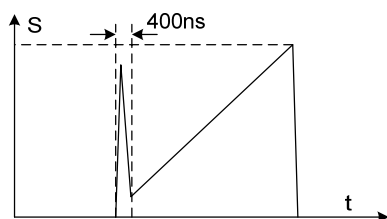


Figure 6: Leading Edge Blanking

### Output Over-Voltage Protection (OVP)

In CC mode, output over-voltage protection (OVP) can prevent the components from damage in an over-voltage condition. The positive plateau of the auxiliary winding voltage is proportional to the LED output voltage. OVP uses the auxiliary winding voltage instead of monitoring the output voltage directly. Once the ZCD voltage is higher than 4.5V for four consecutive periods, the OVP signal is triggered and latched, the gate driver is turned off, and the IC works in quiescent mode. VDD/VCC drops below the UVLO threshold, making the IC shut down and restarting the system. The output OVP setting point can be calculated with Equation (3):

$$V_{OUT\_OVP} \cdot \frac{N_{VCC}}{N_{SEC}} \cdot \frac{R_{ZCD2}}{R_{ZCD1} + R_{ZCD2}} = 4.5V \quad (3)$$

Where  $V_{OUT\_OVP}$  is the output OVP point,  $N_{VCC}$  is the VCC winding turns, and  $N_{SEC}$  is the secondary winding turns.

To avoid the mistriggering OVP by oscillation spikes after the switch turns off, OVP sampling uses a  $t_{LEB\_OVP}$  blanking period (typically 1.5μs) (see Figure 7).

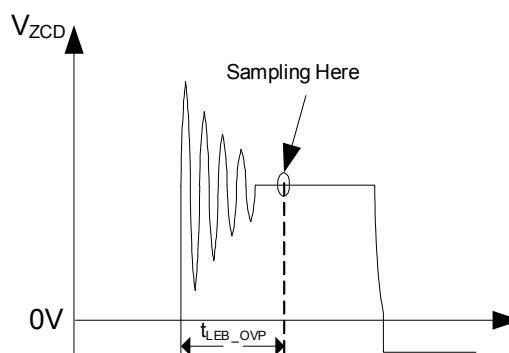


Figure 7: OVP Sample Blanking Time

### Output Short-Circuit Protection (SCP)

If an output short circuit occurs in CC mode, the ZCD cannot detect the zero-current crossing point of the transformer, so the auto-restart timer ( $t_{START}$ ) triggers the turn-on signal of the power MOSFET. In this situation, the switching frequency of the power circuit is reduced, and the output current is limited to its nominal current, so the output power in the output short-circuit condition is very small. The temperature rise of the components is low.

If an output short circuit occurs in CV mode, ZCD may still be detected by the chip for the first several pulses, and the system can be protected by the current limit (typically 0.45V). Afterward, if the ZCD cannot be detected, the auto-restart timer ( $t_{START}$ ) determines the turn-off time, and the foldback value of the current limit determines the turn-on time.

### Brown-Out Protection

Brown-out protection is integrated into the MP4057A. During turn-on, the ZCD voltage can reflect the input voltage. Apply a 350 $\mu$ A current source on ZCD and compare it with 0.2V. If ZCD is higher than 0.2V during turn-on and lasts at least of a half line cycle, the MP4057A recognizes that a brown-out has occurred.

### High-Frequency Mode (HFM) Operation

To achieve a good transient performance, special design is integrated into MP4057A. Figure 8 describe the conditions for entering high-frequency mode (HFM) during CV and CC operation.

Once the MP4057A enters HFM, the slew rate of the sawtooth generator changes from  $\alpha$  to  $\alpha_{transient}$ , and the minimum off time is fixed at  $t_{min\_OFF\_CC}$ . This can help hold the voltage of VO and supply voltage to the MP4057A.

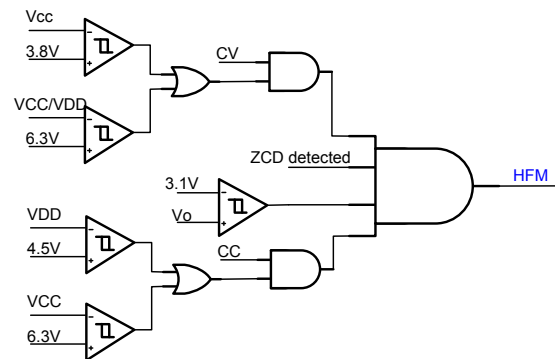
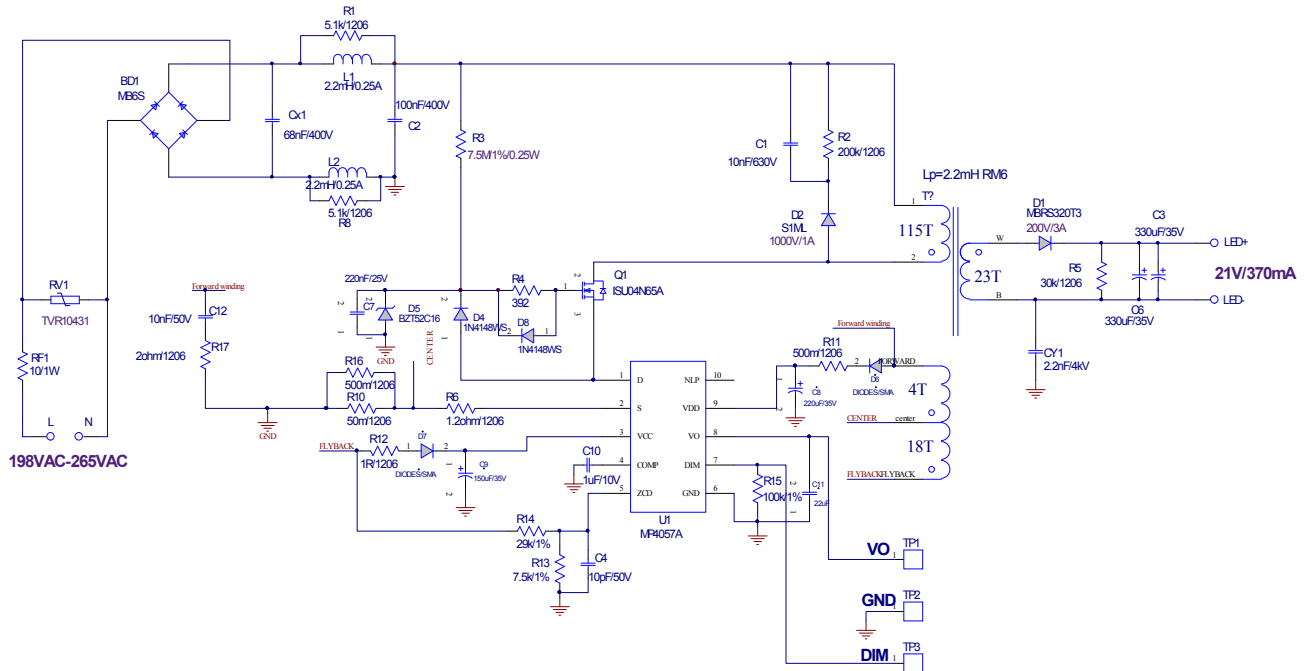


Figure 8: High-Frequency Mode (HFM)

### Thermal Protection

Thermal protection is integrated into the MP4057A. When the junction temperature rises to 160°C, the entire chip shuts down. When the temperature falls back to 90°C, the MP4057A resumes normal operation.

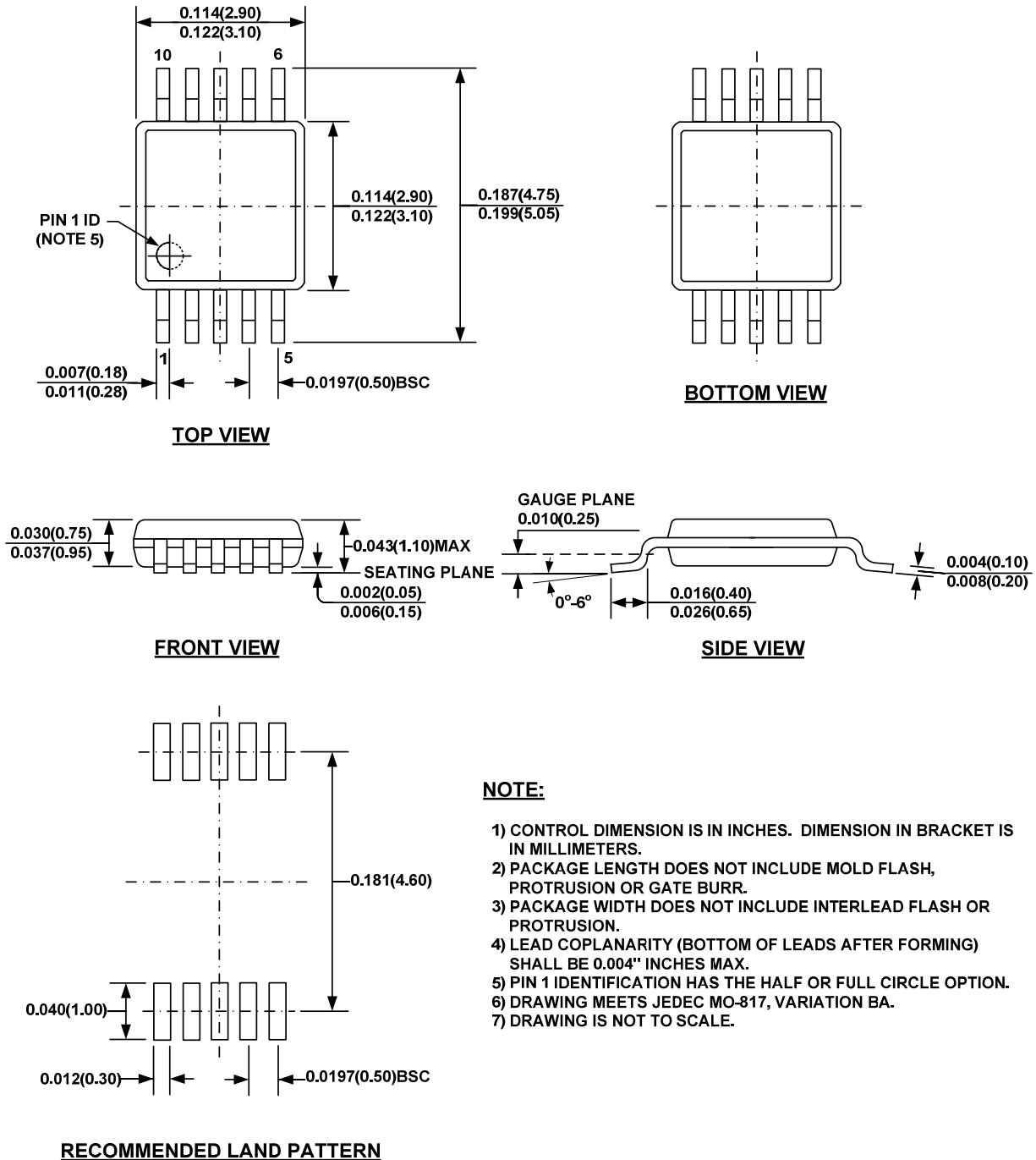
## TYPICAL APPLICATION CIRCUIT



**Figure 9: 230V<sub>AC</sub>/50Hz Input, Isolated Flyback Converter, V<sub>LED</sub> = 21V, I<sub>LED</sub> = 0.37A, V<sub>OUT</sub> = 3.3V, I<sub>OUT</sub> = 50mA  
EVB Model: EV4057A-K-00A**

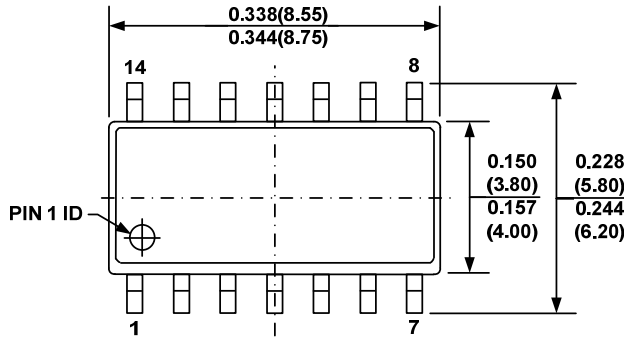
# PACKAGE INFORMATION

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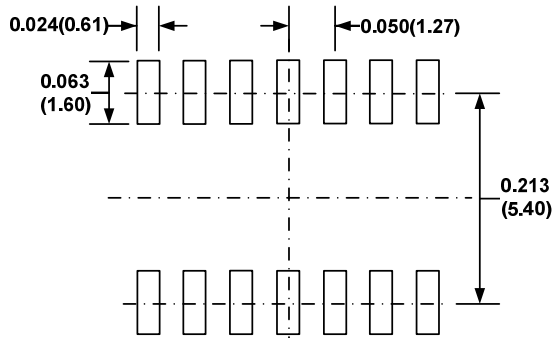


# PACKAGE INFORMATION (continued)

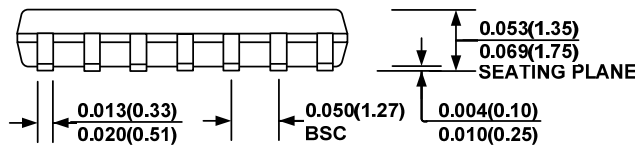
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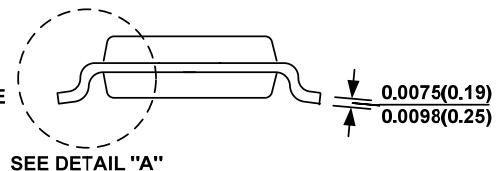
TOP VIEW



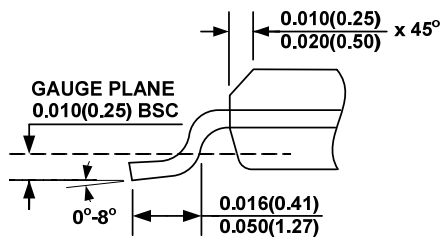
RECOMMENDED LAND PATTERN



FRONT VIEW



SIDE VIEW



DETAIL "A"

### NOTE:

- 1) CONTROL DIMENSION IS IN INCHES. DIMENSION IN BRACKET IS IN MILLIMETERS.
- 2) PACKAGE LENGTH DOES NOT INCLUDE MOLD FLASH, PROTRUSIONS OR GATE BURRS.
- 3) PACKAGE WIDTH DOES NOT INCLUDE INTERLEAD FLASH OR PROTRUSIONS.
- 4) LEAD COPLANARITY (BOTTOM OF LEADS AFTER FORMING) SHALL BE 0.004" INCHES MAX.
- 5) DRAWING CONFORMS TO JEDEC MS-012, VARIATION AB.
- 6) DRAWING IS NOT TO SCALE.

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